

Prof. S. Smith: Wed 5 May 1999

You must SHOW WORK to receive credit.

**Problem 1:**

(a) (flashback to Hour Exam 1) In physics one sometimes sees the set  $S$  of  $3 \times 3$  skew-symmetric matrices—satisfying  $A^T = -A$ . Notice such matrices have the general form  $\begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix}$ .

Show that  $S$  forms a subspace of the space  $\mathbf{R}^{3 \times 3}$  of all  $3 \times 3$  matrices.

$$(\text{closure}, +) \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} + \begin{pmatrix} 0 & d & e \\ -d & 0 & f \\ -e & -f & 0 \end{pmatrix} = \begin{pmatrix} 0 & a+d & b+e \\ -a-d & 0 & c+f \\ -b-e & -c-f & 0 \end{pmatrix}.$$

The sum is also skew, and so still lies in the set  $S$ .

$$(\text{closure}, \text{sc. mult.}) f \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} = \begin{pmatrix} 0 & fa & fb \\ -fa & 0 & fc \\ -fb & -fc & 0 \end{pmatrix}, \text{ also skew, so in } S.$$

(b) (and to Exam 2:) Let  $S$  be the subspace of  $\mathbf{R}^3$  spanned by  $(1, 1, 1)^T$  and  $(1, 2, 3)^T$ . Find  $S^\perp$ .

Put in as rows of  $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix}$ , solve  $Ax = 0$  to get  $x_3(1, -2, 1)^T$ .

**Problem 2:** Let  $A = \begin{pmatrix} 0 & 2 \\ 2 & 0 \end{pmatrix}$ . (a) Find the eigenvalues of  $A$ .

$\det(A - xI) = x^2 - 4 = (x - 2)(x + 2)$  so eigenvalues are  $2, -2$ .

(b) Find the eigenspaces for those eigenvalues. Is  $A$  diagonalizable? Why/why not?

For  $2$ : Solve  $(A - 2I)x = 0$  with  $\begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix}$  to get  $a(1, 1)^T$ ;

For  $-2$ :  $(A + 2I)x = 0$  with  $\begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}$  to get  $b(1, -1)^T$ .

Diagonalizable—distinct eigenvalues (not repeated).

**Problem 3:** Given the differential equation system (functions of  $t$ ):  $\begin{pmatrix} y_1' & = & y_1 & + & 3y_2 \\ y_2' & = & 3y_1 & + & y_2 \end{pmatrix}$ .

GIVEN: the matrix  $\begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix}$  has eigenvalues  $4, -2$ ; with eigenvectors  $(1, 1)^T$  and  $(1, -1)^T$ .

(a) Give the *general* solution of the system (with undetermined constants  $c_1, c_2$ ).

$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} c_1 e^{4t} \\ c_2 e^{-2t} \end{pmatrix} \text{ so } y_1 = c_1 e^{4t} + c_2 e^{-2t} \text{ and } y_2 = c_1 e^{4t} - c_2 e^{-2t}.$$

(b) Now determine the values of  $c_1, c_2$  for the initial value problem  $y_1(0) = 8, y_2(0) = 4$ .

$$\text{Solve } \begin{pmatrix} 1 & 1 & | & 8 \\ 1 & -1 & | & 4 \end{pmatrix} \text{ to get } c_1 = 6, c_2 = 2. \text{ So } y_1 = 6e^{4t} + 2e^{-2t} \text{ and } y_2 = 6e^{4t} - 2e^{-2t}.$$

**Problem 4:** (a) Let  $A$  be the (Markov) matrix  $\begin{pmatrix} \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{2}{3} \end{pmatrix}$ .

Indicate the “steady-state” vector; that is, a vector  $v$  such that  $Av = v$ —and the coordinates of  $v$  add up to 1.

We need an eigenvector for eigenvalue 1. Solve  $(A - 1.I)x = 0$

using  $\begin{pmatrix} -\frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & -\frac{2}{3} \end{pmatrix}$ , to get solutions  $a(2, 3)^T$ ; so use vector  $\frac{1}{5}(2, 3)^T$ .

(b) Is the symmetric matrix  $A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{pmatrix}$  positive definite? Why/why not?

No: for example, determinants of principal minors are 1, -1, 0; not all positive.

**Problem 5:** (a) Let  $A$  be the matrix  $\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$ . GIVEN:  $A$  has eigenvalues 0, 1, 2.

Find eigenvectors, and diagonalize  $A$  (that is, give  $X$  such that  $X^{-1}AX$  is diagonal).

For 0: get  $a(1, 0, -1)^T$ . For 1: get  $b(0, 1, 0)^T$  For 2: get  $c(1, 0, 1)^T$ . So  $X = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix}$ .

(b) The matrix  $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$  has eigenvalues 2, 0 and eigenvectors  $(1, 1)^T$  and  $(1, -1)^T$ . Find  $e^A$ .

We can diagonalize  $A$  with  $X = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ . So from  $A = XDX^{-1}$  we have  $e^A = Xe^DX^{-1} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} e^2 & 0 \\ 0 & e^0 = 1 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} e^2 + 1 & e^2 - 1 \\ e^2 - 1 & e^2 + 1 \end{pmatrix}$

**Problem 6:** Let  $A$  be the symmetric matrix  $\begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$ . GIVEN:  $A$  has eigenvalues 1, 1, 4.

(a) Find a basis for each eigenspace.

For 4: find eigenspace spanned by  $(1, 1, 1)^T$ . For 1: Get eigenvectors  $(-b - c, b, c)^T$ .

So one basis is  $(1, -1, 0)^T$  and  $(1, 0, -1)^T$ .

(b) Use Gram-Schmidt to find an orthonormal basis for each eigenspace. Use that to build an orthogonal matrix  $X$  (that is,  $X^{-1} = X^T$ ) with  $X^{-1}AX$  diagonal.

For 4, just use  $\frac{1}{\sqrt{3}}(1, 1, 1)^T$ . For 1, apply Gram-Schmidt to get  $\frac{1}{\sqrt{2}}(1, -1, 0)^T$  and  $\frac{1}{\sqrt{6}}(1, 1, -2)^T$ .

So can use  $X = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{pmatrix}$ .